

Approximation beyond P

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Quick recall: the problems discussed, the two established solution paradigms and a basic question

Generate a “small” number of candidate solutions

Split the instance (divide & approximate)

Approximately prune the search tree

Optimally solve a “small” part of the instance

Combine polynomial approximation with the techniques above

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The problems

- MAX INDEPENDENT SET:** Given a graph $G(V, E)$, MAX INDEPENDENT SET consists of finding a set $S \subseteq V$ of maximum size such that for any $(u, v) \in S \times S$, $(u, v) \notin E$
- MAX CLIQUE:** Given a graph $G(V, E)$, MAX CLIQUE consists of finding a set $K \subseteq V$ of maximum size such that for any $(u, v) \in K \times K$, $(u, v) \in E$
- MIN SET COVER:** Given a set C of cardinality n and a system $S = \{S_1, \dots, S_m\} \subseteq 2^C$, MIN SET COVER consists of determining a minimum size subsystem S' such that $\bigcup_{S \in S'} S = C$

More problems

MIN COLORING: Given a graph $G(V, E)$, MIN COLORING consists of partitioning the vertex-set V of G into a minimum number of independent sets.

MIN INDEPENDENT DOMINATING SET: Given a graph $G(V, E)$, MIN INDEPENDENT DOMINATING SET consists of finding the smallest independent set of G that is maximal for the inclusion

Polynomial approximation (1)

$\text{opt}(I)$: the value of an optimal solution of an instance I of a problem Π

$m(A, I, S)$: the value of the solution S computed by an approximation algorithm A on I

Approximation ratio of A

$$\rho(A, I) = \max \left\{ \frac{m(A, I, S)}{\text{opt}(I)}, \frac{\text{opt}(I)}{m(A, I, S)} \right\}$$

The closer the ratio to 1, the better the performance of A

Polynomial approximation (2)

Inapproximability result

A statement that a problem is not approximable within ratios better than some approximability level unless something very unlikely (e.g., $P = NP$) happens in complexity theory

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For the problems discussed in this talk:

- ▶ MAX INDEPENDENT SET, MAX CLIQUE, MIN INDEPENDENT DOMINATING SET, MIN COLORING inapproximable within ratios $\Omega(n^{1-\epsilon})$, $\forall \epsilon > 0$
- ▶ MIN SET COVER within ratios $o(\log n)$

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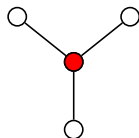
- ▶ Exhaustively generate any subset of V and get a maximum one among those that are independent sets: $O(2^n)$ (trivial exact complexity)
- ▶ Find all the maximal independent sets of the input graph: $O(1.4422^n)$

Exact computation with worst-case bounds (2)

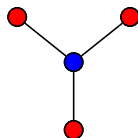
Pruning the search tree

Fix a vertex of maximum degree (> 2 , else the problem is polynomial) and:

- ▶ either don't take it and delete it from the instance
- ▶ or take it and delete it from the graph together with its neighbors



(a) 1 vertex fixed

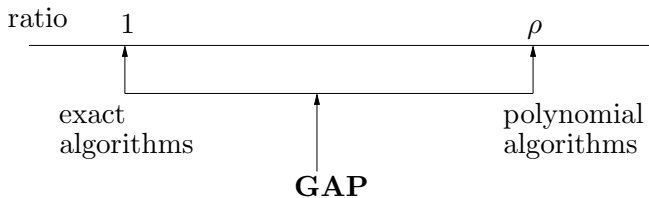


(b) ≥ 4 vertices fixed

$$T(n) \leq T(n-1) + T(n-4) + p(n) \quad ' \quad O(1.385^n)$$

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- ▶ How to bridge **GAP**?

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Worst-case complexity: $O\left(\binom{n}{\sqrt{n}}\right) \leq O\left(2^{\sqrt{n} \log n}\right)$

Subexponential

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- ▶ Solve the problem in this set
- ▶ Compose a solution for the initial instance using the solutions of the sub-instances

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- ▶ Split G into r induced subgraphs G_i of order n/r
- ▶ Optimally solve MAX INDEPENDENT SET in every G_i
- ▶ Output the best among the solutions computed

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S^* : a maximum independent set in G

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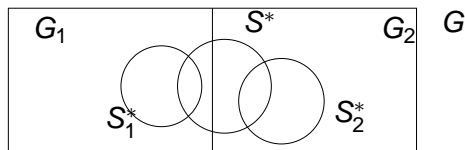
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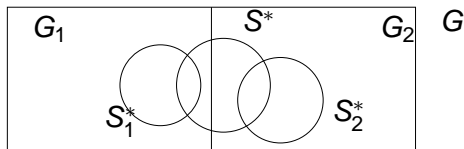


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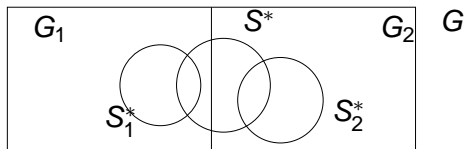
$$\begin{aligned} |S^* \setminus V(G_i)| &\leq |S_i^*| \implies |S^*| \leq |S_1^*| + |S_2^*| \leq 2 \max\{|S_1^*|, |S_2^*|\} \\ &\implies \frac{|S^*|}{\max\{|S_1^*|, |S_2^*|\}} \leq 2 \end{aligned}$$

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Complexity: $O(\gamma^{n/2})$

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Assume that an optimal solution for MAX INDEPENDENT SET can be found in $O(\gamma^n)$
Then, for any fixed $r \geq 2$, an r -approximation for MAX CLIQUE can be computed with complexity $O(\gamma^{r\Delta})$
where Δ is the maximum degree of the input-graph

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CLIQUE can be computed with complexity $O(\gamma^{r\Delta})$

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- ▶ Split G into n induced subgraphs $G_i = G[\{v_i\} \cup \Gamma(v_i)]$, solve MAX INDEPENDENT SET in G_i (recover cliques in G_i 's) and output the best

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The key idea

Perform a branch-and-cut by allowing a “bounded error” in order to accelerate the algorithm (i.e., **make the instance-size decreasing quicker than in exact computation by keeping the produced error “small”**)

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- ▶ Solve recursively the two resulting subinstances and output the best solution computed

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Any branching reduces the number of sets by r : $O(2^{m/r})$

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If the optimum takes $\alpha(G)$ vertices the algorithm above takes at least $\alpha(G)/2$ vertices (all the randomly removed vertices belonged to the optimum)

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Optimally solve the problem in a “small” part of the input and (eventually) approximately extend the solution to fit the whole instance

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For any $k \geq 3$, it is possible to enumerate all independent dominating sets (i.e., maximal independent sets) of size at most n/k with running time $O(k^{n/k})$

- ▶ In Step 2 ratio 1, in Step 3 ratio r
- ▶ Complexity of Step 1: $O(r^{n/r}) = O(2^{n \log r/r})$

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Complexity: $T(n) = T(n-1) + T(n-8) \leq \dots$

BREAK